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The CO₂MPAS tool

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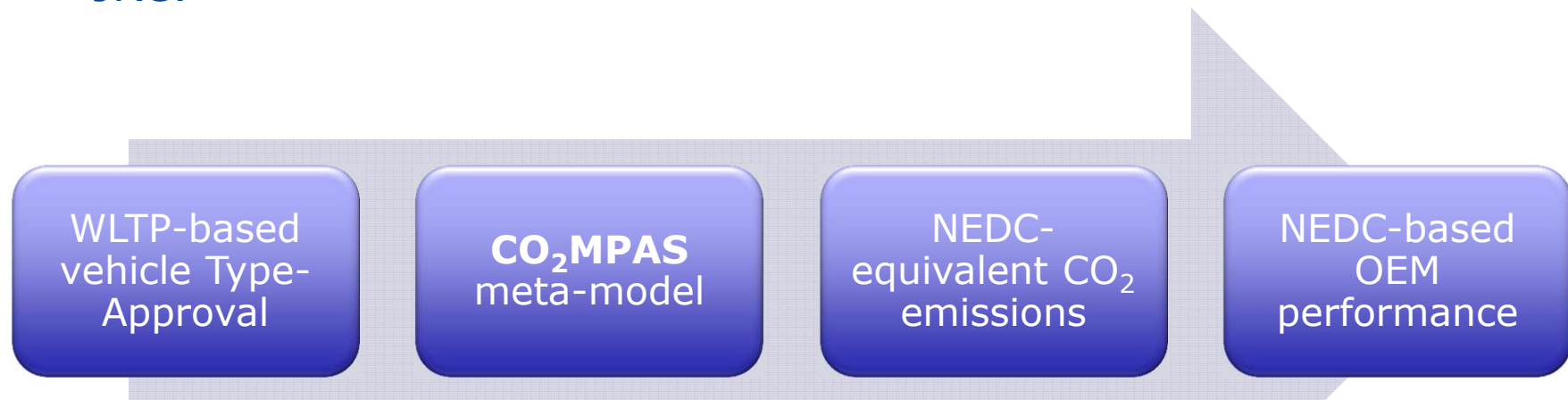
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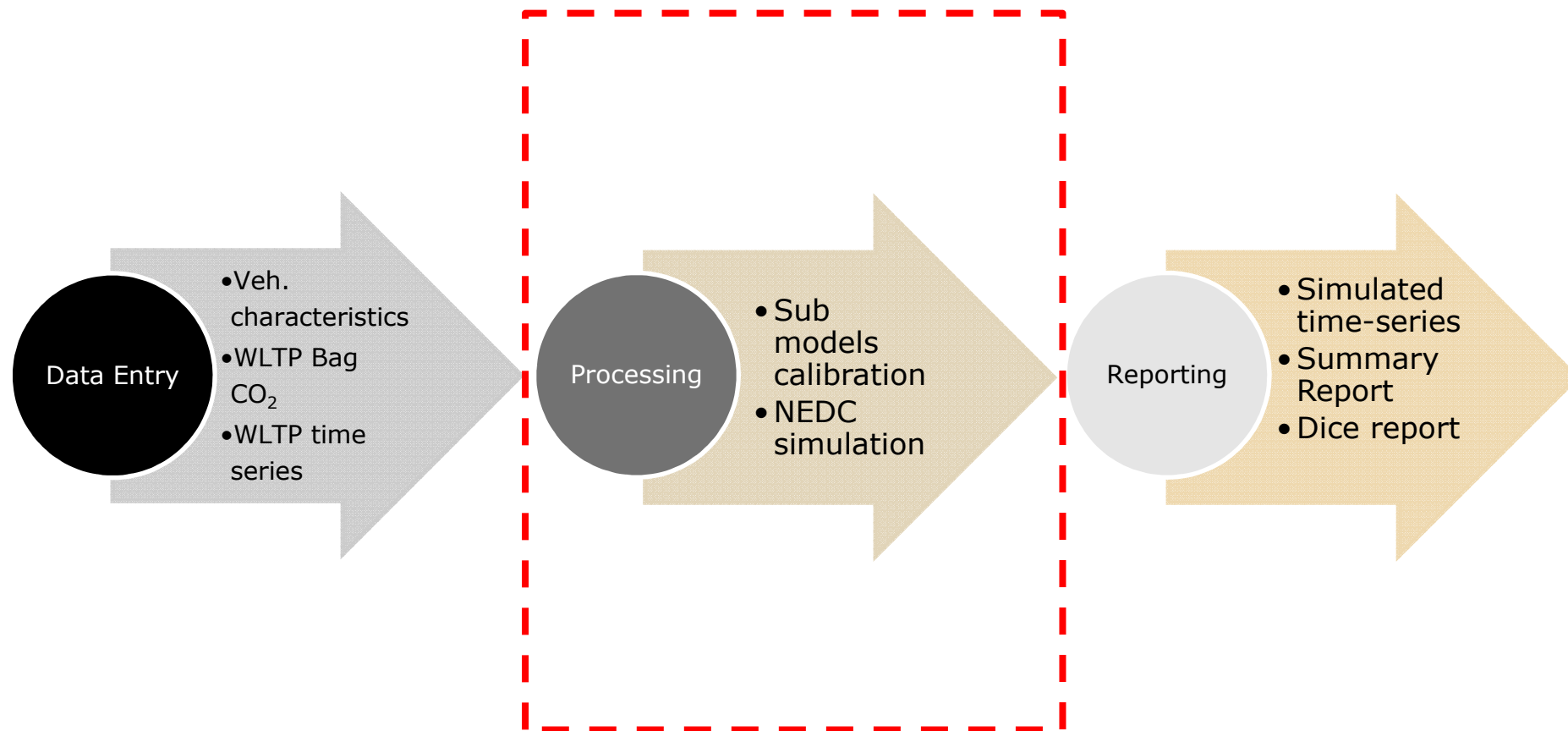


Approach – Phasing-in

- During the **WLTP phasing-in**, WLTP measurements will be correlated into NEDC values using CO₂MPAS (CO₂ Model for Passenger and commercial vehicles Simulation), developed by JRC.



CO₂MPAS data flow overview



Key features

- Comprises of 2 main calculation modules

Power – RPM module

- Simple longitudinal dynamics (WLTP-GTR)
- Engine power and RPM calc'd @ 1hz
- Inclusion of Mech or Elec. loads where needed
- Generic start-stop logic
- A/T and CVT RPM prediction model
- Alternator logic calibrated over WLTP

FC module

- Calculation of FC
Indicative instantaneous approach
- Based on an extended Willans model
- Semi-physical empirical cold start model
- Calibration - Optimization based on WLTP results
- Specific engine technologies included

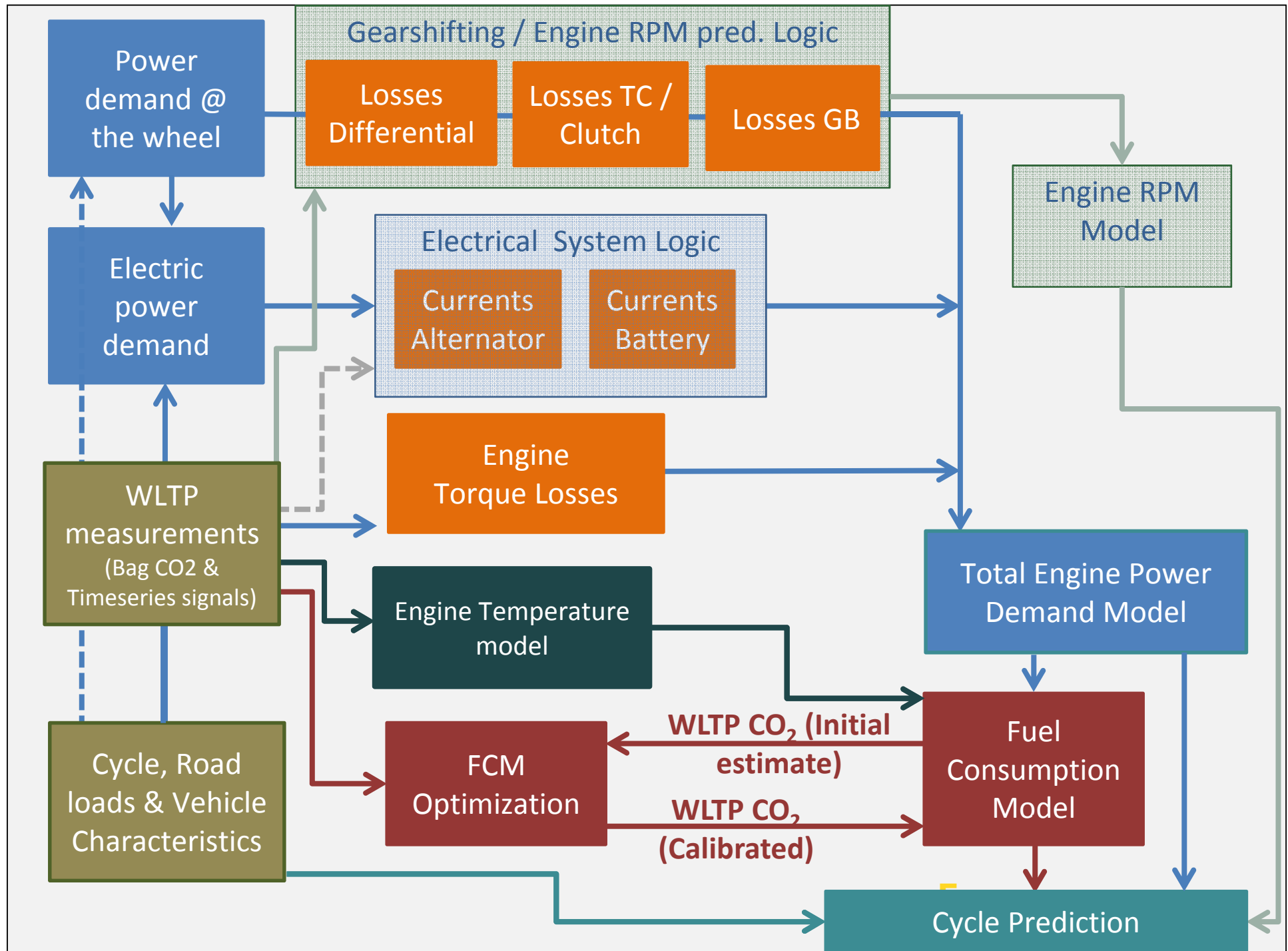
+Parallel work for HEV control module and optimization



Accurate calculation of average / instantaneous power demand



Very good accuracy when compared with results obtained from the Cruise simulations by LAT and **Real test data from 40 vehicles**



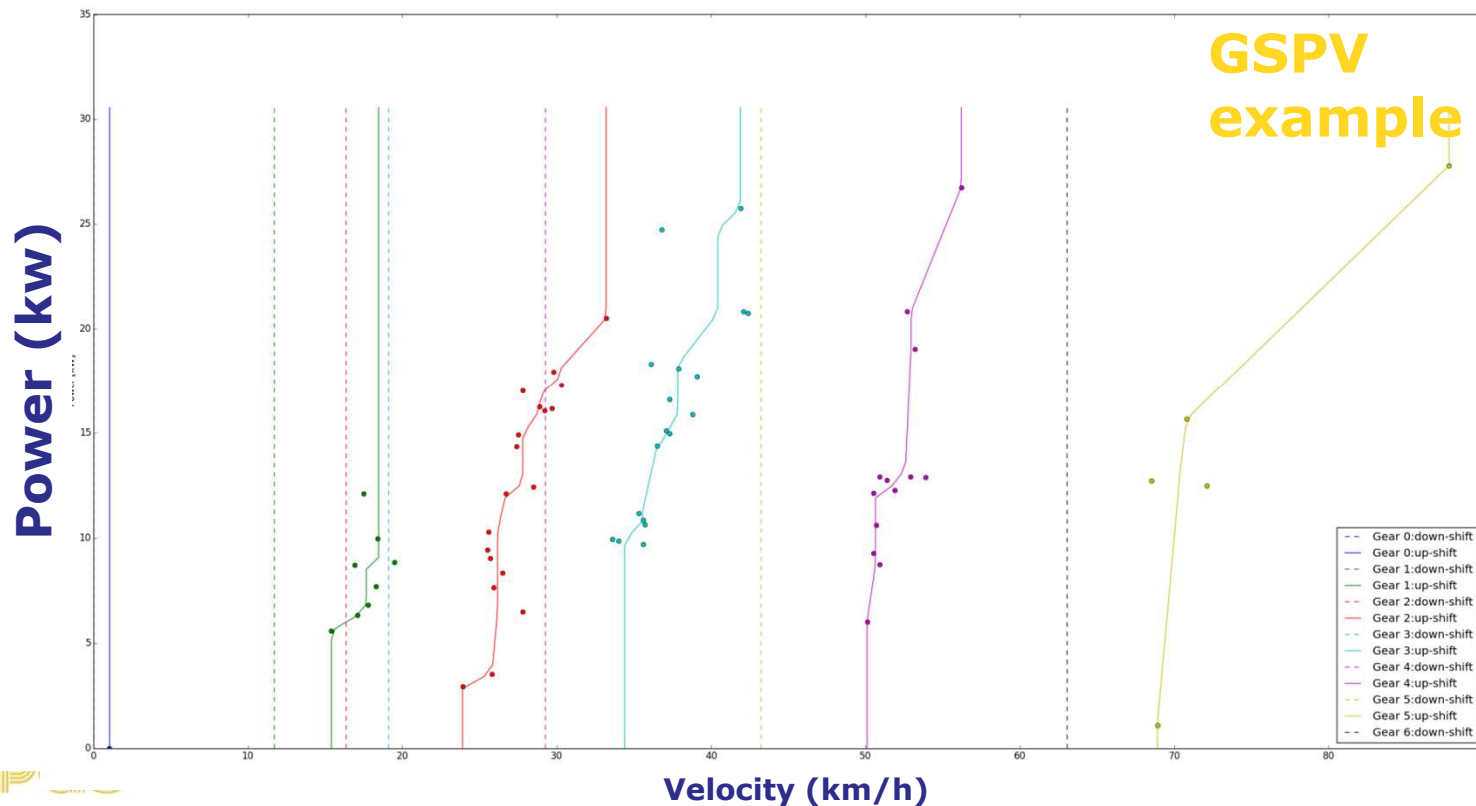
CO₂MPAS sub-models

- CO₂MPAS includes the following sub-models:
 - **Automatic Transmission model (gear shifting)**
 - **Clutch / Torque converter model score**
 - **Engine cold start speed model**
 - **Engine speed model**
 - **Start stop model**
 - **Alternator model**
 - **Engine coolant temperature model**
 - **Engine fuel consumption (CO₂) model**



Automatic Transmission model (gear-shifting 1/2)

- There are 2 **official** options enabled in the A/T model:
 - Corrected Mean Velocity (**CMV**) creates a “map” of gear upshifts and down-speeds as a function of vehicle speed.
 - GearShift Power-Velocity (**GSPV**) creates a map of gear upshifts as a function of vehicle speed & the power at the gearbox
- CO₂MPAS automatically selects the option that better reproduces gear shifting over WLTP
- In engineering mode the DT option can be also enabled



Automatic Transmission model (gear-shifting 2/2)

- Two sets of gear-shift maps are calculated, **hot** and **cold** conditions
- Final step: Matrix Velocity Limits (**MVL**) correction model corrects gear-shifting over quasi-steady state conditions (enables lower gears)
- For **CVTs** a gradient boost regressor is used to predict Engine RPM as a function of vehicle speed, acceleration and power at the gearbox



Clutch / Torque converter model

- CO₂MPAS by default calibrates a clutch model (generic or DTC) unless a TC is declared as present on the vehicle:
 - **In both cases an “RPM-slip” model as a function of acceleration is fitted based on experimental data**
- Efficiency model (predefined non calibrated):
 - **Clutch: linear TC efficiency as a function of RPM ratio**
 - **TC: a non-linear efficiency as a function of RPM ratio**
- For TCs a lock up velocity (48km/h) is used

Engine cold start speed model

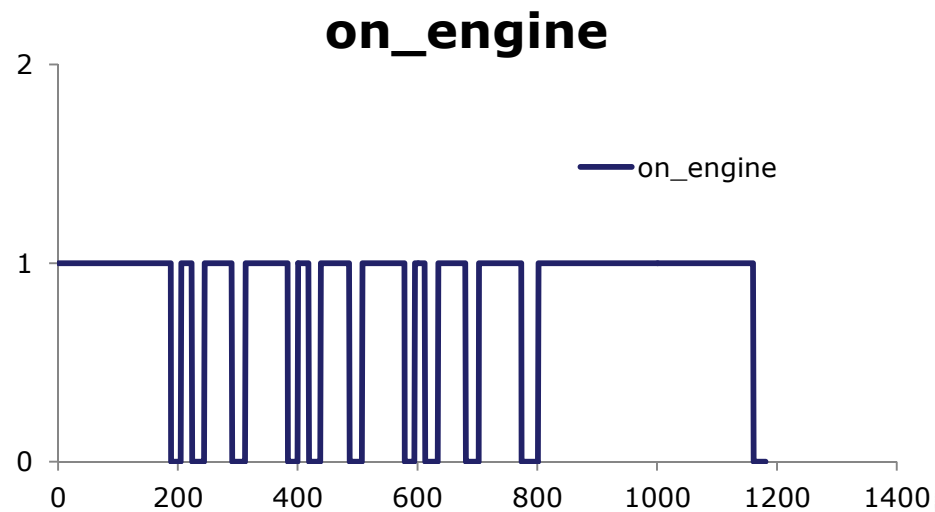
- The ECSSM increases idling RPMs during the cold start phase
- An optimizer is used to calculate the unit less $\Delta\text{RPM}_{\text{idle}}$ [%] function during cold start
- ΔRPM is a linear function of engine temperature capped at a certain value which is also estimated by the optimizer

Engine speed model

- The ESM calculates the exact RPM/Velocity ratios over the specific test
- Gear ratios (or default RPM/V ratios) and information on tyre dimensions provided by the user are used as starting values
- An optimizer calculates the optimal dynamic radius of the tire based on the dyno velocity and engine RPM data measured over the WLTP

Start stop model

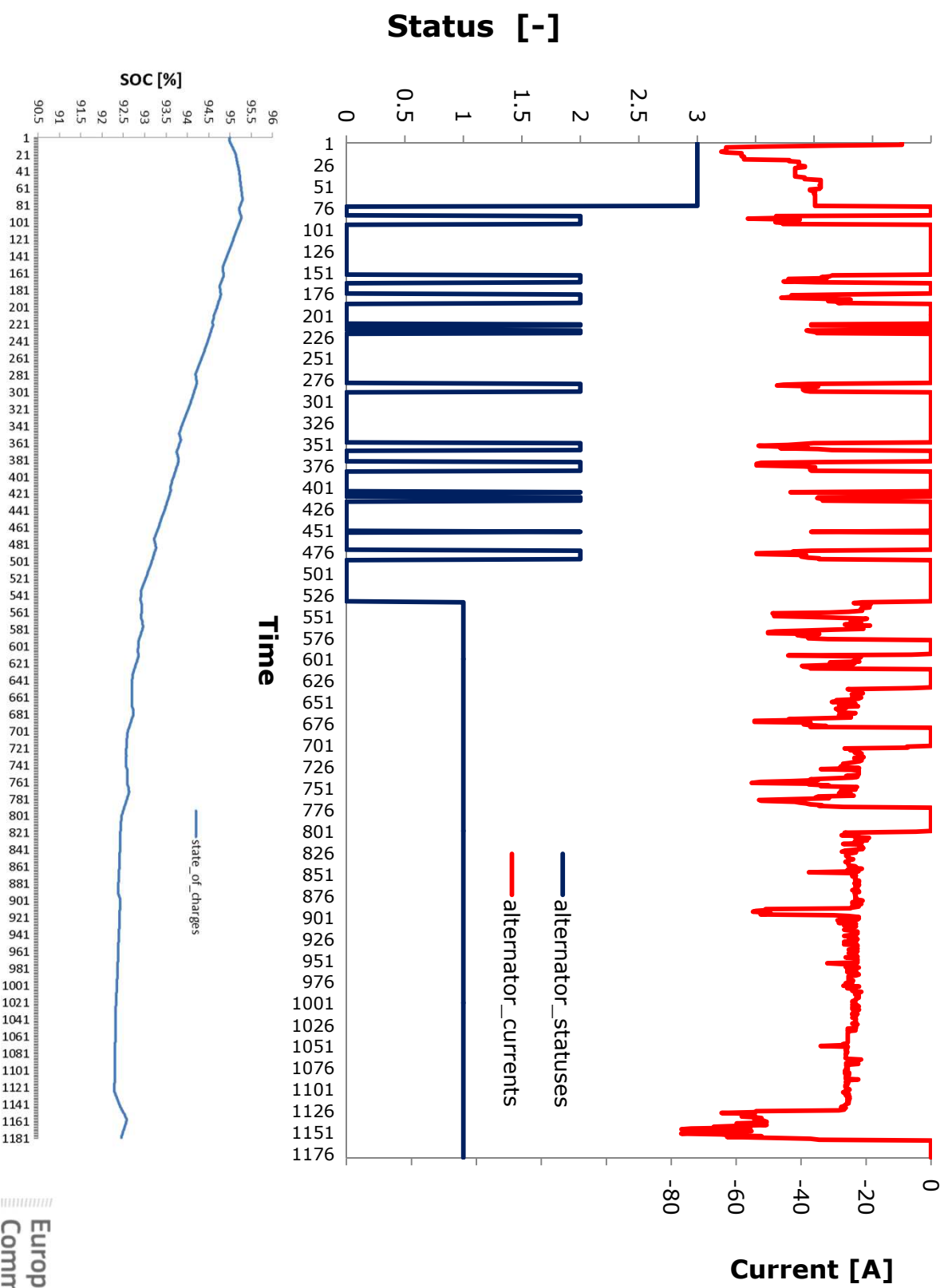
- The SS model defines where the engine should be switched off for SS equipped vehicles
- CO₂ MPAS uses a classifier in order to associate engine switch off events to vehicle deceleration and velocity.
- SS functionality is initiated based on the user provided input on engine SS initiation time



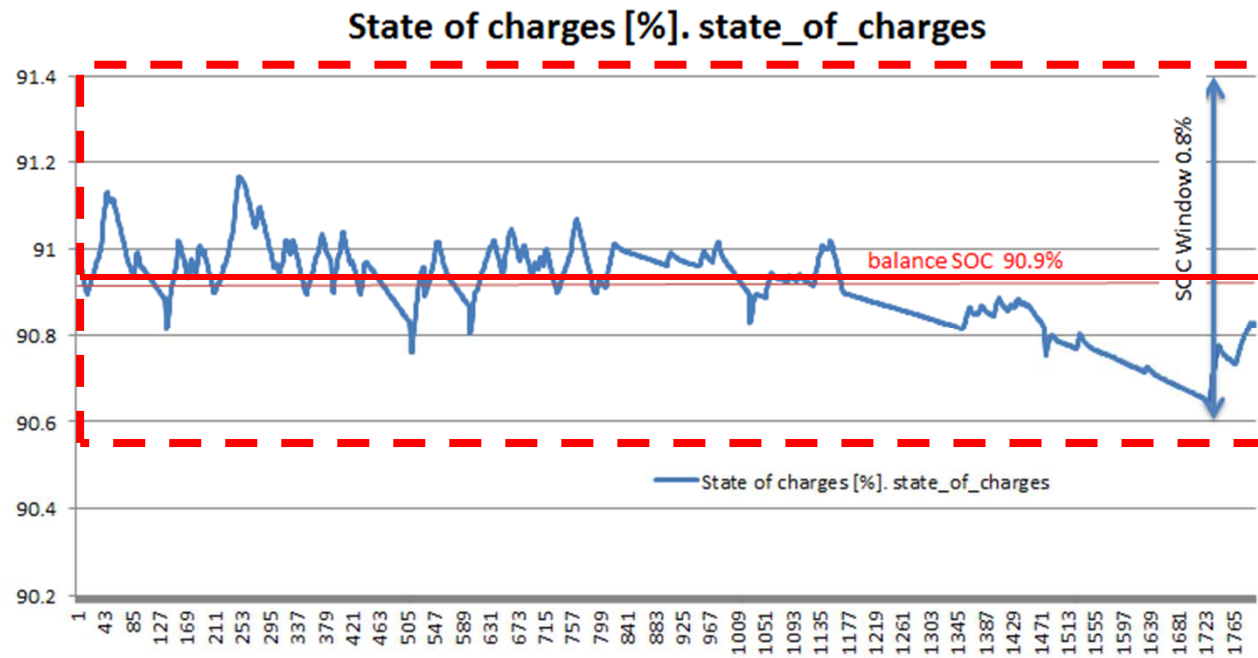
Alternator model

- Comprises of 2 parts:
 - **Logic part (when the alternator operates and how)**
 - **Electric part (what current is supplied by the alternator)**
- **Logic part** identifies different phases (idling, regenerative braking, battery charging, battery depletion) and under what conditions those occur → result: alternator status
- **Electric part** identifies the current per each phase based on other parameters (eg RPM, Battery SOC, deceleration)
- A gradient boost regressor is used for predicting the currents based on alt. status, acceleration, power at g/box, SOC at t-1, and initialization time

Alternator logic and current prediction



Alternator logic and current prediction - windows



Engine coolant temperature model

- CO₂MPAS uses a regressor to predict engine temperature (T) evolution
- T_i is function of T_{i-1} , RPM, acceleration and the power at the gearbox
- The regressor is calibrated based on WLTP recorded time series using Gradient Boost algorithm (ransac algorithm used for inlier and outlier detection)

Engine fuel consumption (CO₂) model

- Extended Willans Model approach:
- Fitting of a specific non-linear Willans model

$$\text{BMEP} = (a + b \times \text{cm} + c \times \text{cm}^2) \times \text{FuMEP} + (a_2 \times \text{FuMEP}^2) + I_0 + I_2 \times \text{cm}^2$$

- Where:
 - **BMEP: brake mean effective pressure**
 - **cm: mean piston speed**
 - **FuMEP: fuel mean effective pressure**
 - **a, b, c, a₂, I₀, I₂ are the parameters that are being fitted**



Engine fuel consumption (CO₂) model

Fuel Consumption (Fc) Calculation Function

$$\int FMEP(t) dt = \int \frac{-\left(a + b * C_m(t) + c * C_m(t)^2\right) + \sqrt{\left(a + b * C_m(t) + c * C_m(t)^2\right)^2 - 4 * a_2 * \left(\left(\frac{T(t)}{T_{target}}\right)^{-k} * (l + l_2 * C_m(t)^2) - BMEP(t)\right)}}{2 * a_2} dt$$

Cold start factor

, where:

- $C_m(t)[m/s] = 2 * \frac{Engine\ Speed\ [rpm]}{60} * Engine\ Stroke\ [m]$
- $BMEP(t)[Pa] = \frac{2 * Engine\ Power\ [W]}{(Engine\ Capacity\ [m^3] * Engine\ Speed\ [rpm]/60)}$
- $Fuel\ Consumption(t)[g/s] = \frac{FMEP(t)[Pa] * Engine\ Capacity\ [m^3] * Engine\ Speed\ [rpm]/60}{2 * Fuel\ Lower\ Heating\ Value\ [J/g]}$

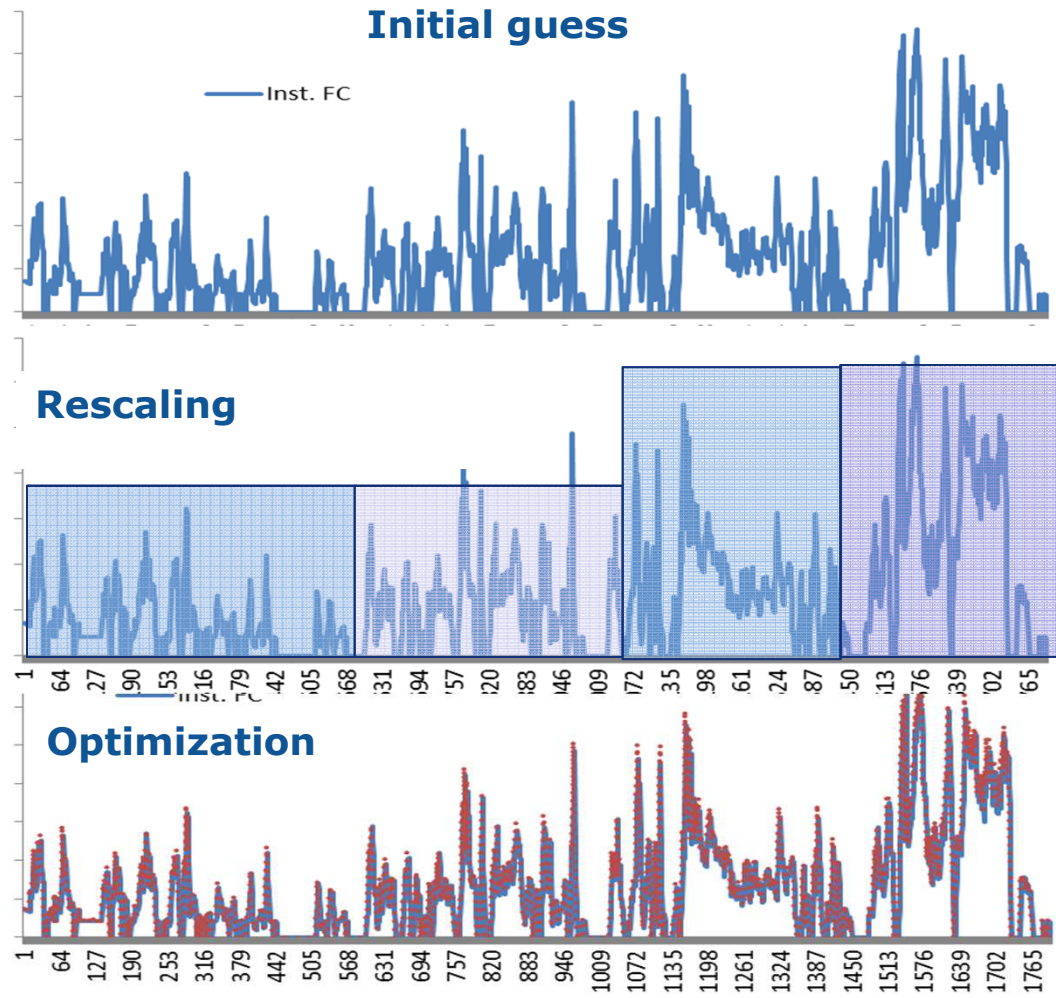
The following are considered as knowns from the measurement / other COMPAS modules (in order to understand issues and improve the stability of the FC module):

- Engine Speed, Temperature, Engine Power
- The constant parameters are calculated by optimization of the above equation against WLTP CO₂ measured data

Engine fuel consumption (CO₂) model

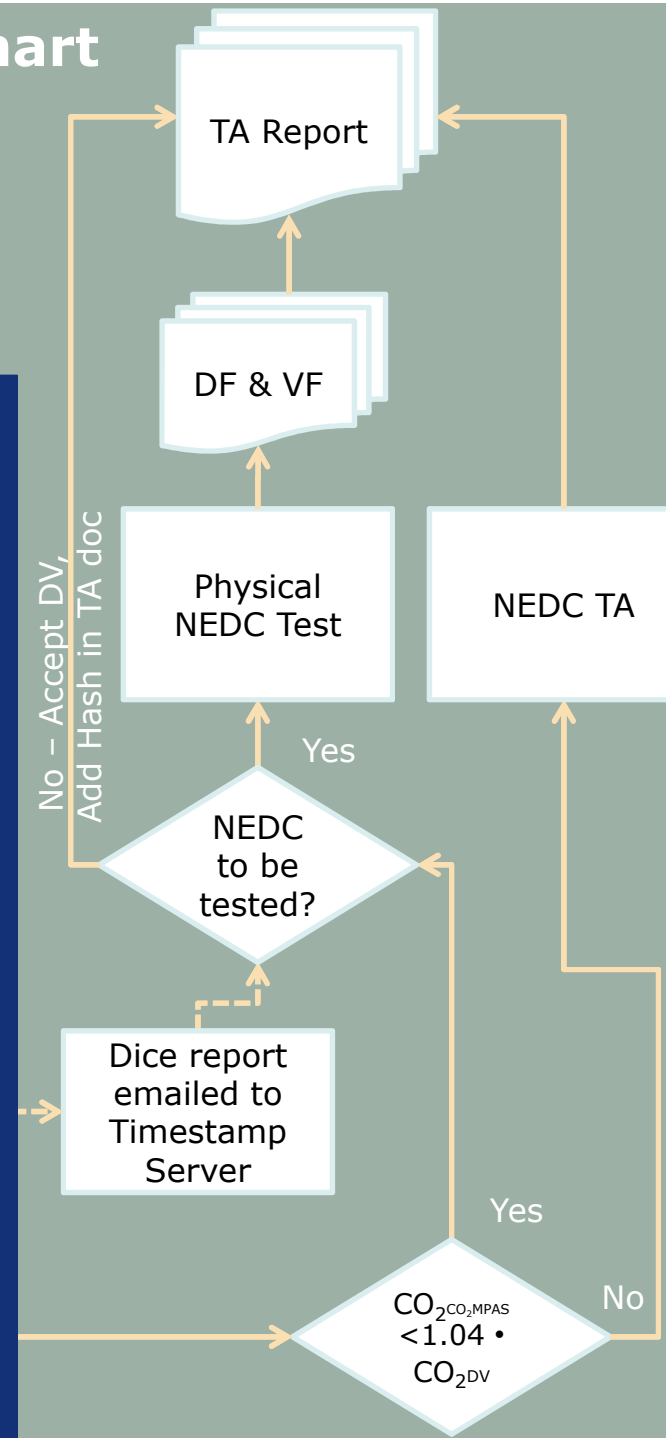
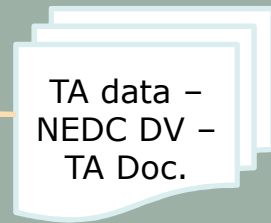
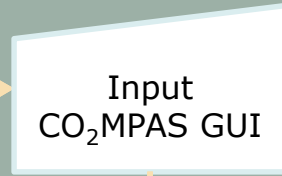
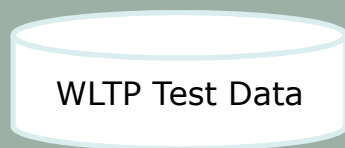
- Extended Willans Model is calibrated using WLTP CO₂ results
 - An initial estimate is made based on generic values (categorized per engine and aspiration type)
 - The model perturbs until the initial and final estimate of the CO₂ time series converge
 - A final optimization is done in order to reduce the error in the WLTP bag value prediction.
- Specific technologies are currently considered using the Extended Willans approach
 - For Petrol engines: Variable valve actuation, Lean combustion, Aspiration type, Cylinder deactivation (limited validation), External EGR (limited validation)
 - For Diesel engines: External EGR, Cylinder deactivation (limited validation), Selective catalytic reduction (limited validation)

Optimization path

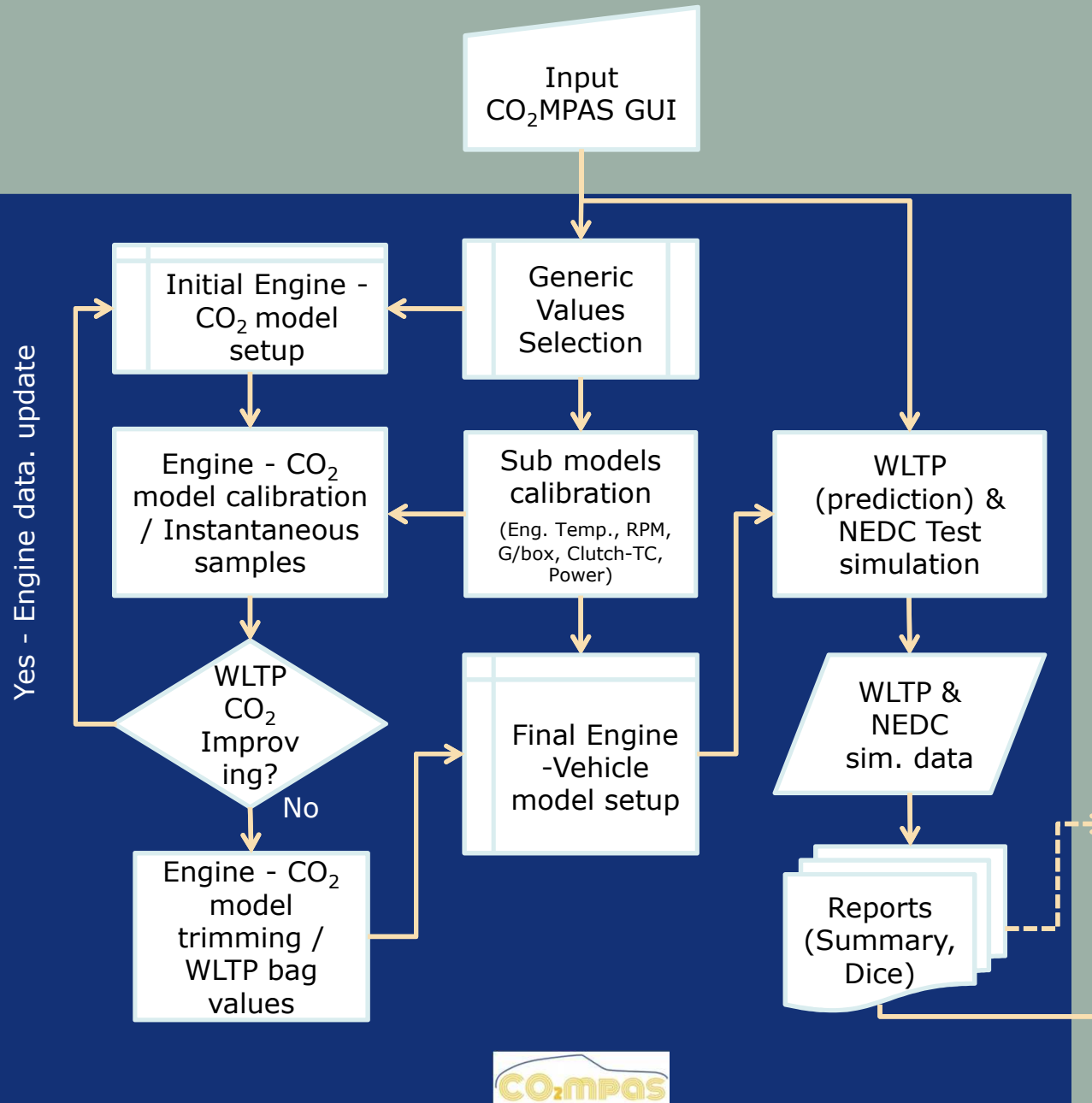


Summary

Correlation and CO₂MPAS Process flow chart



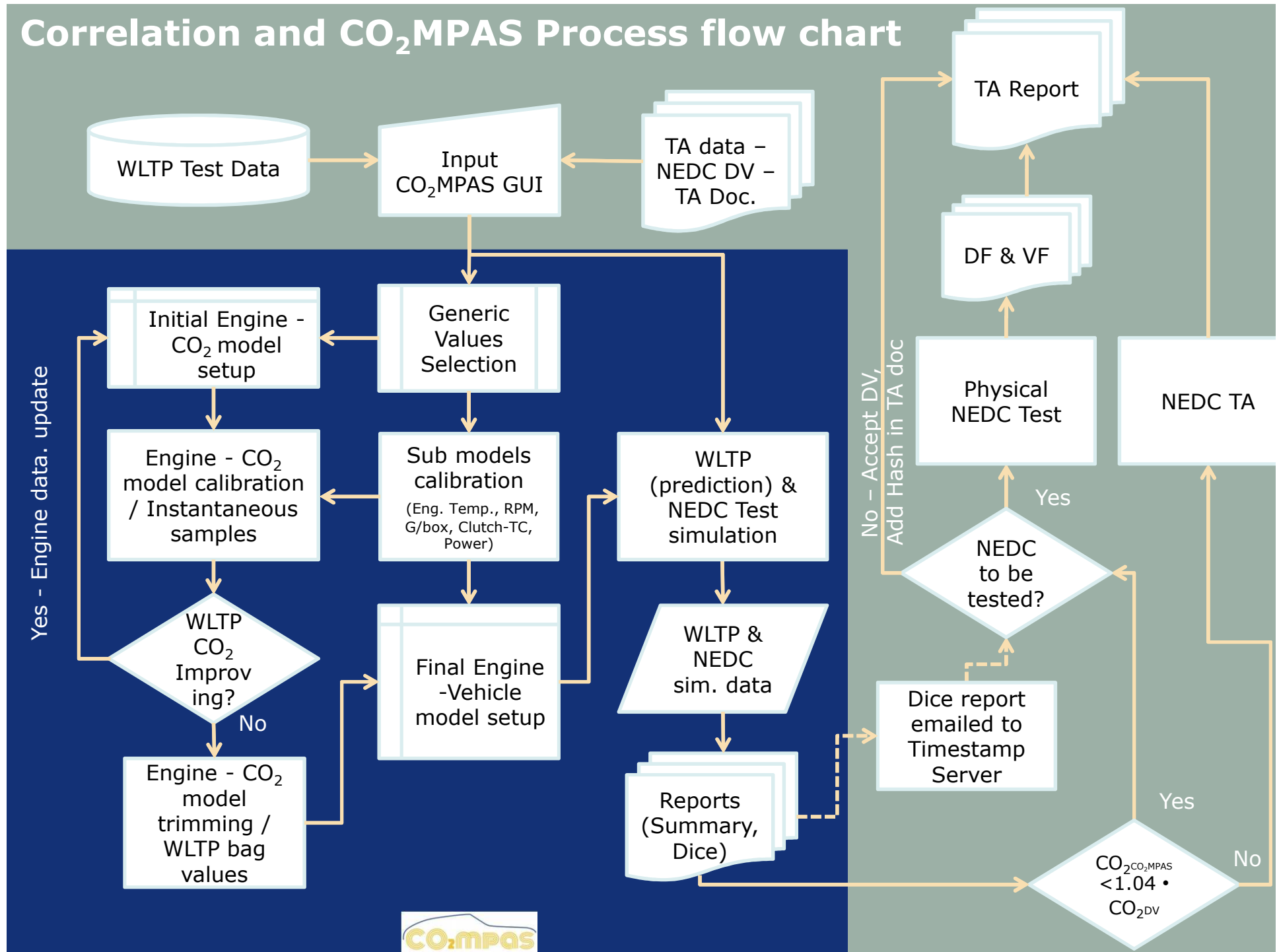
Correlation and CO₂MPAS Process flow chart



Procedures!
Space



Correlation and CO₂MPAS Process flow chart





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